00163

The Open University of Sri Lanka
Faculty of Engineering Technology
Department of Electrical and Computer Engineering

Study Programme	: Bachelor of Software Engineering Honours
Name of the Examination	:Final Examination
Course Code and Title	**: EEX5376 Embedded Systems and IoT**
Academic Year	: 2023/24
Date	: 25th January 2025
Time	: 930-1230hrs
Duration	: **3 hours**

General Instructions

1. Read all instructions carefully before answering the questions.

2. This question paper contains three (3) questions in SECTION A and three (3) questions in SECTION B on **five (5)** pages.

3. Answer all questions in SECTION A.[60 Marks], and answer any Two questions from SECTION B.[40 Marks].

4. Answer for each question should commence from a new page.

5. Refer to the Annexure of the Arduino programming syntax given on page four (4) to write anArduino programming code

6. This is a Closed Book Test(CBT).

7. Answers should be in clear handwriting.

8. Do not use Red colour pen.

Section A:Answer ALL questions [60 Marks]

The following description is about the **Smart Parking Management System (SPMS)**. Your task is to analyse the following specifications and design the **SPMS** *by Providing IoT solutions for a smart city.*

A Smart Parking Management System (SPMS) integrates hardware and software components to efficiently manage and monitor parking areas. By leveraging interconnected devices and parking management applications, SPMS automates various processes, including entry and exit control, payment collection, slot allocation, and security monitoring. The primary objectives of such a system are to optimise parking slot utilisation, reduce congestion, and enhance the overall user experience. By digitising and automating manual tasks, SPMS replaces traditional parking systems, improving efficiency and accuracy.

The hardware components of the system include access control devices such as barriers, gates, ticket dispensers, vehicle identification systems, and payment stations. These components collaborate to regulate access, issue tickets or digital passes, and facilitate payment transactions seamlessly.

Implementing an IoT-based SPMS in Sri Lanka, where there are approximately 900,000 registered motor cars, can significantly improve transportation infrastructure. Such a system utilises real-time data to deliver key features, including: ***Parking Access Control, Real-Time Parking Guidance, Reservations, Digital Payments, Vehicle Detection and Tracking, Intelligent Analytics and Reporting****.*

The system also streamlines ***the entry and exit process****. Dedicated entry and exit points are equipped with sensors to detect vehicle presence, identification devices to verify access, and barrier gates to control flow. Once a vehicle passes through, sensors close the gates automatically. In emergencies, the system can guide vehicles to selected exit gates and automatically open them for evacuation.*

Parking facilities will include designated areas for disabled individuals, private parking, public parking, and EV charging. Access to these areas will be based on real-time parking slot availability. Additionally, data collected at the central station enables the prediction of usage trends, empowering parking managers to optimise operations and enhance revenue generation.

Propose a design for the **SPMS** by executing an IoT solution to provide better transportation to everyone. Accordingly, answer the following questions.

[Q1]

From the global perspective,draw an edge-fog-cloud IoT architecture diagram for the proposed SPMS solution and provide brief explanation. Clearly indicate what the edge devices, gateways, fog devices, connectivity, cloud services, and applications are.

[16 Marks]

[Q2]

Draw the following diagrams for the entry and exit process of the SPMS solution and briefly explain each. [32 Marks]

(i) Process specification diagram.
(ii) Domain model specification diagram.
(iii) Information model specification diagram
(iv) Service specification diagram

[Q3]

Briefly explain three security concerns related to the proposed SPMS solution and the steps that could be taken to mitigate them. [12 Marks]

SECTION B: Answer any TWO questions. [40 Marks]

[Q4]

(i) Create a flow chart for the entry and exit process in the proposed **SPMS** solution, considering a sampling rate of 5-second intervals. [10 Marks]

(ii) Refer to the Arduino programming instructions and write a program for the Q4.(i) process. State the comments where necessary. [10 Marks]

[Q5]

(i) Briefly describe the SPMS IOT solution from a global context. [4 Marks]
(ii) Briefly describe three (3) challenges faced when applying the IoT concept to the **SPMS** application. [6 Marks]
(iii) Draw the block diagram and briefly describe the distributed view of the data processing architecture of the proposed **SPMS** IoT application. (*Hint: Should discuss the types of data used in each level or layer, type of data analysis, and level or layer where it applied*) [10 Marks]

[Q6]

(i) Compare the edge, fog, and cloud computing. [4 Marks]
(ii) Compare and contrast the MQTT, C0AP, and HTTP data transfer protocols and justify data transfer selection for the proposed **SPMS** solution. [8 Marks]
(iii) Briefly explain three (03) lightweight data transfer techniques for your proposed **SPMS** solution.(*hint: should be discussed about techniques of Payload minimisation, Data aggregation, Data compression, etc...*). [8 Marks]

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Annexure

Syntax of selected instructions of the Arduino programming

Structure & Flow

Basic program structure

```
void setup () {
    // Runs once when sketch starts
}
void loop () {
   //Runs repeatedly
}
```

Control Structures

```
If (x < 5) {.....} else {.....}
while (x < 5) {.....}
for ( int i = 0; i< 10; i++) {.....}
break;      // Exit a loop immediately
continue;   // Go to next iteration
switch (var) {
case 1:
  .....
break;
   case 2:
 .....
break;
   default:
 .....
}
return x;   // x must match return type
return;     // For void return type
```

Function Definitions

<ret. type><name> (params) {.....}
e.g. int double (int x) {return x*2;}

Operators

General operators

= assignment
+ add - subtract
* multiply / divide
% modulo
== equal to != not equal to
<less than > greater than
<= less than or equal to
>= greater than or equal to
&& and || or
! not

Compound operators

++ increment
-- decrement
+= compound addition
-= compound subtraction
*= compound multiplication
/= compound division
&= compound bitwise and
|= compound bitwise or

Bitwise Operators

& bitwise and | bitwise or
^ bitwise xor ~ bitwise not
<< shift left >> shift right

Pointer Access

& reference: get a pointer
* dereference: follow a pointer

Variables, Arrays, and Data

Data types

bool	true	|	false
char	-128	-	127, 'a' '$' etc.
unsigned char	0	–	255
byte	0	–	255
int	-32768	-	32767
unsigned int	0	–	65535
word	0	–	65535
long	-2147483648	–	2147483647
unsigned long	0	–	4294967295
float	-3.4028e+38	–	3.4028e+38

double currently same as float
void return type: no return value

Strings

```
char str1[8] =
    {'A', 'r', 'd', 'u', 'i', 'n', 'o', '\0'};
    // Includes \0 null termination
char str2[8] =
    {'A', 'r', 'd', 'u', 'i', 'n', 'o', };
    //Compiler adds null termination
char str3[] = "Arduino";
char str4[8] = "Arduino";
```

Numeric Constants

123 decimal
0b01111011 binary
0173 octal – base 8
0x7B hexadecimal – base 16
123U force unsigned
123L force long
123UL force unsigned long
123.0force floating point
1.23e61.23*10^6 = 1230000

Qualifiers

Static persists between calls
volatilein RAM (nice for ISR)
const read-only
PROGMEMin flash

Arrays

```
byte mypins []  =  {2, 4, 8, 3, 6};
int myInts [6];        // Array of 6 ints
myInts[0] = 42;        // Assigning first
                       // Index of myInts
myInts[6] = 12;        // ERROR! Indexes
                       // are 0 though 5
```

Built – in Functions

Pin Input / Output
Digital I/O – pins 0 – 13 A0 – A5
PinMode(pin,
{ INPUT | OUTPUT | INOUT_PULLUP})
int **digitalRead**(pin)
digitalWrite(pin, {HIGH | LOW})

Analog In – pins A0 – A5
Int **analogRead** (pin)
analogReference(
{DEFAULT | INTERNAL | EXTERNAL})

PWM Out – pins 3 5 6 9 10 11
analogWrite(pin, value) // 0-255

Advanced I/O
tone(pint, freq_Hz, [duration_msec])
noTone(pin)
shiftOut(dataPin, clockPin,
{MSBFIRST | LSBFIRST}, value)
shiftIn(dataPin, clockPin,
{MSBFIRST | LSBFIRST})
unsigned long pulseIn(pin,
{HIGH | LOW}, [timeout_usec])

Time
unsigned long millis()
// overflows at 50 days
unsigned long micros()
// overflow at 70 minutes
delay(msec)
delayMicroseconds(usec)

Math
min(x, y)**max**(x, y) **abs**(x)
sin(rad) **cos**(rad) **tan**(rad)
sqrt(x) **pow**(base, exponent)
constain(x, minval, maxval)
map(val, fromL, fromH, toL, toH)

Random Numbers
randomSeed(sced) // long or int
long random(max) // 0 to max-1
long random(min, max)

Bits and Bytes
lowByte(x) **highByte**(x)
bitRead(x, bitn)
bitWrite(x, bitn, bit)
bitSet(x, bitn)
bitClear(x, bitn)
bit(bitn) // bitn: 0=LSB 7=MSB

Type Conversions
char(val)**byte**(val)
int(val) **word**(val)
long(val) **float**(val)

External Interrupts
attachInterrrupt(interrupt, func,
{LOW | CHANGE | RISING | FALLING})
detachInterrupt(interrupt)
interrupts()
noInterrupts()

Libraries

serial – comm.with pc or via RX/TX
begin(long speed) // up to 115200
end()
int **available()** // #bytes available
int **read()**// -1 if none available
int **peek()** // Read w/o removing
flush()
print(data)println(data)
write(byte) write(char*string)
write(byte*data, size)
serialEvent() // called if data rdy

softwareSerial.h – comm. on any pin
softwareSerial (rxpin, txpin)
begin(long speed) // up to 115200
listen() // only 1 can listen
isListening() // at aitme.
read, peek, print, println, write
// Equivalent to serial library

EEPROM.h – access non-voLatile memory
byte read(addr)
write(addr, byte)
EEPROM[index] // Access as array

Servo.h – control servo motors
attach(pin, [min_usec, max_usec])
write(angle)// 0 to 180
writeMicroseconds(us)
// 1000-2000; 1500 is midpoint
int read()// 0 to 180
bool attached()
detach()

wire.h – I C communication
begin() // Join a master
begin(addr) // Join a salve @ addr
requestFrom(address, count)
beginTransmission(addr) // step 1
send(byte) // step 2
send(char*string)
send(byte*data, size)
endTransmission() // step 3
int avaialable() // #bytes available
byte receiver() // get next byte
onReceive(handler)
onRequest(handler)